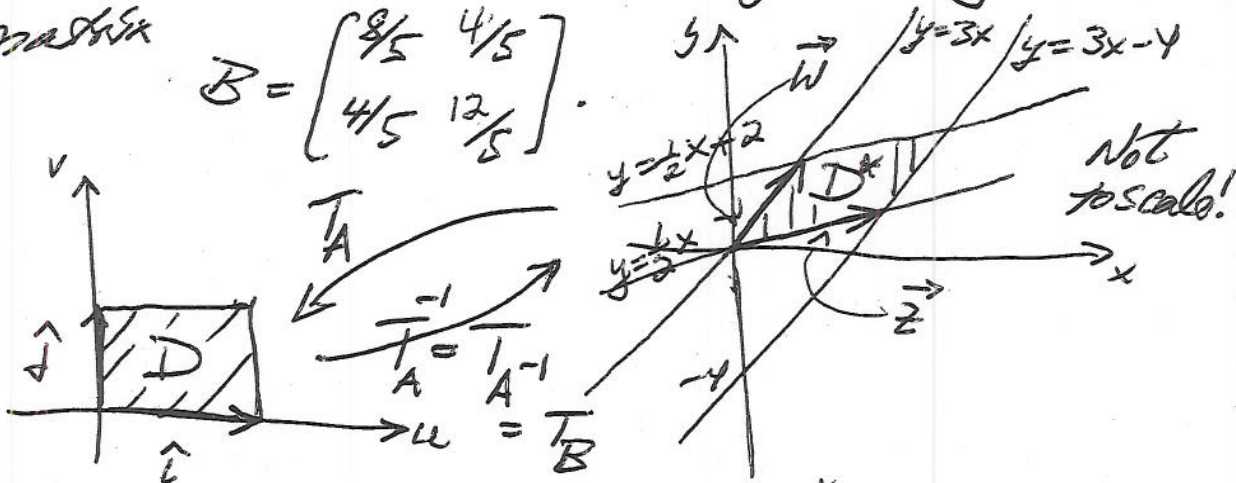


6.1 #4 It is actually easier to find  $B = A^{-1}$  and  $T_B = T_A^{-1}$  by using the observation that  $B e_i = i^{\text{th}}$  column of  $B$ . Now  $D^*$  is spanned by the vectors  $\vec{z} = \begin{bmatrix} 8/5 \\ 4/5 \end{bmatrix}$  and  $\vec{w} = \begin{bmatrix} 4/5 \\ 12/5 \end{bmatrix}$ . Take  $T_B$

$[0,1] \times [0,1] \rightarrow D^*$  to be given by the matrix

$$B = \begin{bmatrix} 8/5 & 4/5 \\ 4/5 & 12/5 \end{bmatrix}$$



It is a tedious calculation\* then to compute  $A = B^{-1} = \begin{bmatrix} 3/4 & -1/4 \\ -1/4 & 1/2 \end{bmatrix}$ . You can then

check that  $T_A(\vec{z}) = \begin{bmatrix} 1 \\ 0 \end{bmatrix} = \hat{i}$  and  $T_A(\vec{w}) = \begin{bmatrix} 0 \\ 1 \end{bmatrix} = \hat{j}$  by using left mult. by  $A$ .

Notice  $T_B(u, v) = \begin{bmatrix} 8/5 & 4/5 \\ 4/5 & 12/5 \end{bmatrix} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} 8/5u + 4/5v \\ 4/5u + 12/5v \end{bmatrix}$

$= (x, y)$ , so what have essentially done is to solve  $\begin{cases} x = 8/5u + 4/5v \\ y = 4/5u + 12/5v \end{cases}$  for  $(u, v)$

in terms of  $(x, y)$ . It is worth comparing  $\frac{\partial(x, y)}{\partial(u, v)}$  with  $\frac{\partial(u, v)}{\partial(x, y)}$ . \* but straight forward & available on demand

Of course it is a bit of a leap of faith to expect  $T$  to be linear, but in retrospect it worked.

6.1 #7 We discussed this one in class.

6.1 #8 You can use some more sophisticated linear algebra, but bare hands also works. Assume  $T = T_A$  where  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ .

I. Claim If  $\det A \neq 0$  then  $T_A$  is one-to-one.

Suppose  $A \begin{bmatrix} x \\ y \end{bmatrix} = A \begin{bmatrix} x' \\ y' \end{bmatrix}$ , a seeming failure of 1-1. We aim to show that actually  $x = x'$  and  $y = y'$ . Put  $z = x - x'$  and  $w = y - y'$ . Then

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} z \\ w \end{bmatrix} = A \begin{bmatrix} z \\ w \end{bmatrix} = A \begin{bmatrix} x - x' \\ y - y' \end{bmatrix} = A \begin{bmatrix} x \\ y \end{bmatrix} - A \begin{bmatrix} x' \\ y' \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\text{So } \begin{cases} az + bw = 0 \\ cz + dw = 0 \end{cases}. \text{ Now } \det A \neq 0$$

means  $ad - bc \neq 0$ ; thus not both  $a = 0$  and  $c = 0$ . By exchanging the equations the argument using  $c \neq 0$  runs just like  $a \neq 0$ , so without loss of generality we may assume  $a \neq 0$ . Then we can divide by  $a$  and solve  $z = -\frac{b}{a}w$ . The second equation becomes

$$c\left(\frac{-b}{a}w\right) + dw = 0 \text{ or } \left(\frac{-cb}{a} + d\right)w = 0.$$

If we get a common denominator then we have  $\frac{(-cb+da)}{a}w = 0$  and since

the quantity in parentheses is not zero (why not?), we conclude  $w = 0$ . It follows that  $z = 0$ , and then  $x = x'$ ,  $y = y'$ , showing that  $T_A$  is 1-1.

II. Claim If  $T_A$  is 1-1, then  $\det A \neq 0$ .

Suppose, to the contrary, that  $ad - bc = \det A = 0$ . Then

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} d \\ -c \end{bmatrix} = \begin{bmatrix} ad - bc \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}.$$

But  $T_A$  is 1-1, and now we have

$$A \begin{bmatrix} d \\ -c \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} = A \begin{bmatrix} 0 \\ 0 \end{bmatrix}. \text{ So it}$$

must be that  $d = c = 0$ . Similarly

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} b \\ -a \end{bmatrix} = \begin{bmatrix} 0 \\ cb - da \end{bmatrix} = \begin{bmatrix} 0 \\ -\det A \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

forces us to conclude that  $b = a = 0$ .

$$\text{But } \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix} \text{ for all } x, y$$

is as far from being 1-1 as a linear transformation can be! So our supposition was false, and in fact  $\det A \neq 0$ .