Math 544, Final Exam Summer 2007

Write your answers as legibly as you can on the blank sheets of paper provided. Use only **one side** of each sheet. Be sure to number your pages. Put your solution to problem 1 first, and then your solution to number 2, etc.; although, by using enough paper, you can do the problems in any order that suits you.

Please leave room in the upper left corner for the staple.

There are **9** problems **on TWO sides**. The exam is worth a total of 100 points. Problem 1 is worth 20 points. All of the other problems are worth 10 points each. SHOW your work. CIRCLE your answer. CHECK your answer whenever possible. **No Calculators.**

If I know your e-mail address, I will e-mail your grade to you. If I don't already know your e-mail address and you want me to know it, then **send me an e-mail**.

You should **KEEP** this copy of your exam.

I will post the solutions on my website later today.

1. Let
$$A = \begin{bmatrix} 1 & 2 & 3 & 6 \\ 2 & 2 & 3 & 7 \\ 3 & 4 & 6 & 13 \\ 1 & 2 & 6 & 9 \end{bmatrix}$$
. Find a basis for the null space of A . Find

a basis for the column space of A. Find a basis for the row space of A. Express each column of A as a linear combination of the basis you have chosen for the column space of A. Express each row of A as a linear combination of the basis you have chosen for the row space of A.

Apply Elementary Row Operations to A to obtain

$$\begin{bmatrix} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

We see that the null space of A is the set of all vectors $\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix}$ with

$$x_1 = -x_4$$

 $x_2 = -x_4$
 $x_3 = -x_4$
 $x_4 = x_4$.

We conclude that

$$\begin{bmatrix} -1\\-1\\-1\\1\end{bmatrix}$$

is a basis for the nullspace of A. The vectors

$$A_{1} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 1 \end{bmatrix}, A_{*,2} = \begin{bmatrix} 2 \\ 2 \\ 4 \\ 2 \end{bmatrix}, A_{*,3} = \begin{bmatrix} 3 \\ 3 \\ 6 \\ 6 \end{bmatrix}$$

are a basis for the column space of A. The vectors

$$\begin{aligned}
 w_1 &= \begin{bmatrix} 1 & 0 & 0 & 1 \\ w_2 &= \begin{bmatrix} 0 & 1 & 0 & 1 \\ w_3 &= \begin{bmatrix} 0 & 0 & 1 & 1 \end{bmatrix} \end{aligned}$$

are a basis for the row space of A. We also see that

$$A_{*,4} = A_{*,1} + A_{*,2} + A_{*,3}$$

and

$$A_{1,*} = 1w_1 + 2w_2 + 3w_3$$

$$A_{2,*} = 2w_1 + 2w_2 + 3w_3$$

$$A_{3,*} = 3w_1 + 4w_2 + 6w_3$$

$$A_{4,*} = 1w_1 + 2w_2 + 6w_3$$

2. Define "linearly independent". Use complete sentences. Include everything that is necessary, but nothing more.

The vectors v_1, \ldots, v_p in the vector space V are linearly independent if the only numbers c_1, \ldots, c_p with $c_1v_1 + \cdots + c_pv_p = 0$ are $c_1 = c_2 = \cdots = c_p = 0$.

3. Let $T\colon V\to W$ be a linear transformation of vector spaces. Let w_1,\ldots,w_b be a basis for the image of T; z_1,\ldots,z_a be a basis for the null space of T; and v_1,\ldots,v_b be vectors in V with $T(v_i)=w_i$ for $1\leq i\leq b$. Prove that the vectors $v_1,\ldots,v_b,z_1,\ldots,z_a$ span V. Recall that the image of T is equal to

$$\{w \in W \mid w = T(v) \text{ for some } v \in V \}.$$

Let v be a vector in V. The vector T(v) is in the image of T; so, T(v) is a linear combination of the vectors w_1, \ldots, w_b (which form a basis for the image of T). In other words, there are numbers c_1, \ldots, c_b with $T(v) = \sum_{i=1}^b c_i w_i$. The hypothesis tells us that $w_i = T(v_i)$ for all i; hence

$$T(v) = \sum_{i=1}^{b} c_i T(v_i).$$

Move everything to one side and use the fact that T is a linear transformation to see that

$$T(v - \sum_{i=1}^{b} c_i v_i) = 0.$$

In other words, $v - \sum_{i=1}^{b} c_i v_i$ is in the null space of T. The vectors z_1, \ldots, z_a form a basis for the null space of the null space of T; hence, $v - \sum_{i=1}^{b} c_i v_i$ can be written as a linear combination of z_1, \ldots, z_a and v can be written as a linear combination of $z_1, \ldots, z_a, v_1, \ldots, v_b$.

4. Let $U \subseteq V \subseteq W$ be vector spaces. Suppose that v_1, v_2, v_3, v_4 is a basis for W. Suppose further that v_1, v_2, v_3 are in V, but v_4 is not in V. Suppose finally, that v_1 and v_2 are in U, but v_3 and v_4 are not in U. What is the dimension of U? Explain your answer VERY THOROUGHLY.

The dimension of U is 2. The vector space V is a proper suspace of the four dimensional vector space W (so $\dim V \leq 3$); furthermore V contains 3 linearly independent vectors; hence, $\dim V = 3$. The vector space U is a proper suspace of the three dimensional vector space V (so $\dim U \leq 2$); furthermore U contains 2 linearly independent vectors; hence, $\dim U = 2$.

5. Let $V = \{p(x) \in \mathcal{P}_3 \mid p'(1) = 0\}$. Is V a vector space? If yes, then find a basis for V. If no, then show why not? (Recall that \mathcal{P}_3 is the vector space of polynomials of degree less than or equal to 3.)

YES. The polynomials

1,
$$(x-1)^2$$
, $(x-1)^3$

form a basis for V.

6. Let $V = \{M \in \operatorname{Mat}_{3 \times 3}(\mathbb{R}) \mid \operatorname{tr}(M) = 0\}$. Is V a vector space? If yes, then find a basis for V. If no, then show why not? (Recall that $\operatorname{Mat}_{3 \times 3}(\mathbb{R})$ is the vector space of 3×3 matrices. The trace of the 3×3 matrix

$$M = \begin{bmatrix} m_{1,1} & m_{1,2} & m_{1,3} \\ m_{2,1} & m_{2,2} & m_{2,3} \\ m_{3,1} & m_{3,2} & m_{3,3} \end{bmatrix}$$

is
$$tr(M) = m_{1,1} + m_{2,2} + m_{3,3}$$
.)

YES. The matrices

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{bmatrix}, \begin{bmatrix} 0 & 1 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

form a basis for V.

7. Let

$$v = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \end{bmatrix}, \quad u_1 = \begin{bmatrix} 1 \\ 1 \\ 1 \\ 1 \end{bmatrix}, \quad u_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}, \quad u_3 = \begin{bmatrix} 1 \\ 0 \\ -1 \\ 0 \end{bmatrix}, \quad \text{and} \quad u_4 = \begin{bmatrix} 0 \\ 1 \\ 0 \\ -1 \end{bmatrix}.$$

Express v as a linear combination of u_1 , u_2 , u_3 , u_4 . (You are encouraged to notice that u_1, u_2, u_3, u_4 form an orthogonal set of vectors.)

Write $v = \sum_{i=1}^4 c_i u_i$. Multiply by $u_1^{\rm T}$ to see that $10 = 4c_1$ (i.e., $c_1 = \frac{5}{2}$). Multiply by $u_2^{\rm T}$ to see that $c_2 = -\frac{1}{2}$. Continue in this manner to see $c_3 = c_4 = -1$. We conclude that $\boxed{\frac{5}{2}u_1 - \frac{1}{2}u_2 - u_3 - u_4 = v}$.

8. Find a matrix B with B^2 equal to $A = \begin{bmatrix} -11 & 15 \\ -20 & 24 \end{bmatrix}$.

Notice that $\begin{bmatrix} 1 \\ 1 \end{bmatrix}$ is an eigenvector of A which belongs to A and $\begin{bmatrix} 3 \\ 4 \end{bmatrix}$ is an eigenvector of A which belongs to A. Thus, AS = BD for $B = \begin{bmatrix} 1 & 3 \\ 1 & 4 \end{bmatrix}$ and $B = \begin{bmatrix} 4 & 0 \\ 0 & 9 \end{bmatrix}$. We take

$$B = S \begin{bmatrix} 2 & 0 \\ 0 & 3 \end{bmatrix} S^{-1} = \begin{bmatrix} 2 & 9 \\ 2 & 12 \end{bmatrix} \begin{bmatrix} 4 & -3 \\ -1 & 1 \end{bmatrix} = \overline{\begin{bmatrix} -1 & 3 \\ -4 & 6 \end{bmatrix}}$$

(Do be sure to check your answer. Mine works.)

9. Find an orthogonal basis for the null space of $A = \begin{bmatrix} 1 & 2 & 1 & 2 \end{bmatrix}$.

One basis for the null space of A is

$$v_1 = \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix}, v_2 = \begin{bmatrix} -1\\0\\1\\0 \end{bmatrix}, v_3 = \begin{bmatrix} -2\\0\\0\\1 \end{bmatrix}.$$

Let
$$u_1 = v_1 = \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix}$$
. Let

$$u_2' = v_2 - \frac{u_1^{\mathrm{T}} v_2}{u_1^{\mathrm{T}} u_1} u_1 = \begin{bmatrix} -1 \\ 0 \\ 1 \\ 0 \end{bmatrix} - \frac{2}{5} \begin{bmatrix} -2 \\ 1 \\ 0 \\ 0 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} -1 \\ -2 \\ 5 \\ 0 \end{bmatrix}.$$

Let

$$u_2 = 5u_2' = \begin{bmatrix} -1\\-2\\5\\0 \end{bmatrix}.$$

(At this point be sure to check that u_2 is in the null space of A and that u_2 is perpendicular to u_1 .) Let

$$u_{3}' = v_{3} - \frac{u_{1}^{\mathrm{T}}v_{3}}{u_{1}^{\mathrm{T}}u_{1}}u_{1} - \frac{u_{2}^{\mathrm{T}}v_{3}}{u_{2}^{\mathrm{T}}u_{2}}u_{2} = \begin{bmatrix} -2\\0\\0\\1 \end{bmatrix} - \frac{4}{5} \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix} - \frac{2}{30} \begin{bmatrix} -1\\-2\\5\\0 \end{bmatrix}$$
$$= \begin{bmatrix} -2\\0\\0\\1 \end{bmatrix} - \frac{4}{5} \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix} - \frac{1}{15} \begin{bmatrix} -1\\-2\\5\\0 \end{bmatrix} = \frac{1}{15} \begin{bmatrix} -5\\-10\\-5\\15 \end{bmatrix} = \frac{-1}{3} \begin{bmatrix} 1\\2\\1\\-3 \end{bmatrix}.$$

Let $u_3 = -3u_3' = \begin{bmatrix} 1\\2\\1\\-3 \end{bmatrix}$. Be sure to verify that u_3 is in the null space of A and

that u_3 is orthogonal to u_1 and u_2 . Our basis for the null space of A is:

$$u_1 = \begin{bmatrix} -2\\1\\0\\0 \end{bmatrix}, \quad u_2 = \begin{bmatrix} -1\\-2\\5\\0 \end{bmatrix}, \quad u_3 = \begin{bmatrix} 1\\2\\1\\-3 \end{bmatrix}.$$