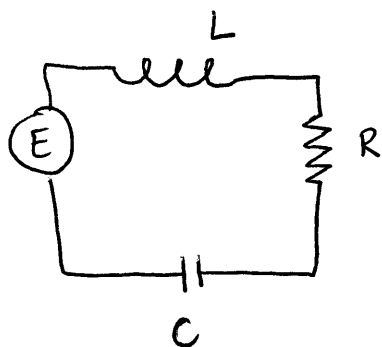


5.1 #48



$$Lq'' + Rq' + \frac{1}{C}q = E(t)$$

$$q(0) = 0$$

$$i(0) = q'(0) = 2$$

$$q'' + 100q' + \frac{1}{0.0004}q = 30$$

$$q'' + 100q' + 2500q = 30$$

$$1) t^2 + 100t + 2500 = 0$$

$$(t + 50)^2 = 0 \quad t = -50 \quad \text{mult. 2}$$

$$q_{\text{hom}} = c_1 e^{-50t} + c_2 t e^{-50t}$$

$$2) q_p = A$$

$$2500A = 30$$

$$q_p' = 0$$

$$A = \frac{3}{250} = \frac{12}{1000} = 0.012$$

$$q_p'' = 0$$

$$\text{So } q(t) = c_1 e^{-50t} + c_2 t e^{-50t} + 0.012$$

$$0 = q(0) = c_1 + 0 + 0.012 \quad c_1 = -0.012$$

$$q'(t) = -50c_1 e^{-50t} + c_2 e^{-50t} - 50c_2 t e^{-50t}$$

$$2 = q'(0) = -50c_1 + c_2 - 0$$

$$c_2 = 2 + 50c_1 = 2 + 50(-0.012) = 2 - 0.6 = 1.4$$

$$q(t) = -0.012 e^{-50t} + 1.4 t e^{-50t} + 0.012 = e^{-50t} (1.4t - 0.012) + 0.012$$

$$q'(t) = e^{-50t} (-50(1.4t - 0.012) + 1.4) = e^{-50t} (-70t + 2)$$

$$q'(t) = 0 \quad \text{if } -70t + 2 = 0 \quad \text{i.e. } t = \frac{2}{70} = \frac{1}{35}$$

Maximum

$$q_{\text{max}} = q\left(\frac{1}{35}\right) = e^{-\frac{50}{35}} (0.04 - 0.012) + 0.012 =$$

$$= \boxed{0.0187C}$$

t	0	$\frac{1}{35}$	$+\infty$
$q'(t)$	+	0	-
$q(t)$		↗ max ↘	

5.1 #52

$$\frac{1}{2} q'' + 20q' + \frac{1}{0.001} q = 100 \sin(60t) + 200 \cos(60t)$$

$$\frac{1}{2} q'' + 40q' + 2000q = 200 \sin(60t) + 400 \cos(60t)$$

$$1) r^2 + 40r + 2000 = 0$$

$$r_{1,2} = \frac{-40 \pm \sqrt{1600 - 8000}}{2} = \frac{-40 \pm \sqrt{-6400}}{2} = \frac{-40 \pm 80i}{2} = -20 \pm 40i$$

$$q_h = c_1 e^{-20t} \cos(40t) + c_2 e^{-20t} \sin(40t)$$

$$2) q_p = A \sin(60t) + B \cos(60t)$$

$$q_p' = 60A \cos(60t) - 60B \sin(60t)$$

$$q_p'' = -3600A \sin(60t) - 3600B \cos(60t)$$

$$-3600A \sin(60t) - 3600B \cos(60t) + 40(60A \cos(60t) - 60B \sin(60t)) + 2000(A \sin(60t) + B \cos(60t)) = 200 \sin(60t)$$

$$\begin{cases} -3600B + 2400A + 2000B = 0 \\ -3600A - 2400B + 2000A = 200 \end{cases}$$

$$\begin{cases} 2400A - 1600B = 0 & | \div 800 \\ -1600A - 2400B = 200 & | \div 200 \end{cases}$$

$$\begin{cases} 3A - 2B = 0 \\ -8A - 12B = 1 \end{cases}$$

$$\begin{aligned} B &= \frac{3}{2}A \\ -8A - 12 \cdot \frac{3}{2}A &= 1 \\ -8A - 18A &= 1 \end{aligned}$$

$$\begin{aligned} -26A &= 1 \\ \boxed{A = -\frac{1}{26}} & \quad \boxed{B = -\frac{3}{52}} \end{aligned}$$

$$q_p(t) = -\frac{1}{26} \sin(60t) - \frac{3}{52} \cos(60t)$$

#52 cont.

$$3) q_{p2} = C \cos 40t + D \sin 40t$$

$$q'_{p2} = -40C \sin 40t + 40D \cos 40t$$

$$q''_{p2} = -1600C \cos 40t - 1600D \sin 40t$$

$$-1600C \cos 40t - 1600D \sin 40t + 40(-40C \sin 40t + 40D \cos 40t)$$

$$+ 2000(C \cos 40t + D \sin 40t) = 400 \cos 40t$$

$$\begin{cases} -1600C + 1600D + 2000C = 400 \\ -1600D - 1600C + 2000D = 0 \end{cases}$$

$$\begin{cases} 400C + 1600D = 400 & 1 \div 400 \\ -1600C + 400D = 0 & 1 \div 400 \end{cases}$$

$$\begin{cases} C + 4D = 1 \\ -4C + D = 0 \end{cases} \quad D = 4C \quad C + 16C = 1 \quad \boxed{C = \frac{1}{17}}$$
$$\boxed{D = \frac{4}{17}}$$

$$q_{p2}(t) = \frac{1}{17} \cos 40t + \frac{4}{17} \sin 40t$$

$$\text{So } q_p(t) = -\frac{1}{26} \sin(60t) - \frac{3}{52} \cos(60t) + \frac{4}{17} \sin(40t) + \frac{1}{17} \cos(40t)$$

The steady-state current is

$$\begin{aligned} \dot{i}_p(t) = q'_p(t) = & -\frac{60}{26} \cos(60t) + \frac{180}{52} \sin(60t) \\ & + \frac{160}{17} \cos(40t) - \frac{40}{17} \sin(40t) \end{aligned}$$