# CONVEX BODIES OF CONSTANT WIDTH AND CONSTANT BRIGHTNESS 

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A convex body in $\mathbf{R}^{n}$ is a compact convex set with non-empty interior. A convex body $K$ in the three dimensional Euclidean space has constant width $w$ iff the orthogonal projection of $K$ onto every line is an interval of length $w$. It has has constant brightness $b$ iff the orthogonal projection of $K$ onto every plane is a region of area $b$.

Theorem 1. Any convex body in $\mathbf{R}^{3}$ of constant width and constant brightness is a Euclidean ball.

Under the extra assumption that the boundary $\partial K$ is $C^{2}$ this was proven by S. Nakajima [4] in 1926. Since then the problem of determining if there is a non-smooth nonspherical convex body in $\mathbf{R}^{3}$ of constant width and constant brightness has become well known among geometers studying convexity. For example see [2, Ques. 2 p. 437], [3].

In the case of bodies with $C^{2}$ boundaries and positive curvature Nakajima's result was generalized by Chakerian [1] in 1967 to "relative geometry" where the width and brightness are measured with with respect to some convex body $K_{0}$ symmetric about the origin called the gauge body. The following isolates the properties of the gauge body needed for the proof of Theorem 1 to generalize. Recall the Minkowski sum of two subsets $A$ and $B$ of $\mathbf{R}^{n}$ is $A+B=\{a+b: a \in A, b \in B\}$.

Definition. A convex body $K_{0}$ is a regular gauge iff it is centrally symmetric about the origin and there are convex sets $K_{1}, K_{2}$ and Euclidean balls $B_{r}$ and $B_{R}$ such that $K_{0}=$ $K_{1}+B_{r}$ and $B_{R}=K_{0}+K_{2}$.

Any convex $K_{0}$ body symmetric about the origin with $C^{2}$ boundary and positive Gaussian curvature is a regular gauge. For any linear subspace $P$ of $\mathbf{R}^{n}$ let $K \mid P$ be the projection of $K$ onto $P$ (all projections in this paper are orthogonal). For any unit vector $u$ let $w_{K}(u)$ be the width in the direction of $u$. For each positive integer $k$ and any Borel subset of $\mathbf{R}^{n}$ be $V_{k}(A)$ be the $k$-dimensional volume of $A$ (which in this paper is defined to be the $k$ dimensional Hausdorff measure of $A$ ). Two subsets $A$ and $B$ are homothic iff there is a positive scalar $\lambda$ and a vector $v_{0}$ so that $B=v_{0}+\lambda A$.
Theorem 2. Let $K_{0}$ be a regular gauge in $\mathbf{R}^{3}$ and let $K$ be any convex body in $\mathbf{R}^{3}$ such that for some constants $\alpha, \beta$

$$
w_{K}(u)=\alpha w_{K_{0}}(u), \quad V_{2}\left(K \mid u^{\perp}\right)=\beta V_{2}\left(K \mid u^{\perp}\right)
$$

for all $u \in \mathbb{S}^{n-1}$. Then $K$ is homothic to $K_{0}$.

## References

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Date: 14 March, 2003.

