### Curvelets and Approximation Theory

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Mathematicians are like Frenchmen: Whatever you say to them, they translate into their own language and forthwith it is something entirely different.

Johan Wolfgang von Goethe



#### Outline Transforms

Curvelet Transforms Analysis with Curvelets

# Outline

### Curvelet Transforms

- Background and Motivation
- Continuous Curvelet Transform
- Discrete Curvelet Transform

### 2 Analysis with Curvelets

- Curvelets and Singularities
- Curvelets and Cartoons
- Curvelets and Besov Spaces



Background and Motivation Continuous Curvelet Transform Discrete Curvelet Transform

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### Curvelets then and now

• Curvelets were introduced in 1999 by Candès and Donoho to address the edge representation problem. The definition they gave was based on windowed ridgelets.





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- In 2003, they developed a Continuous Curvelet Transform.

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angle \Phi_{lphaeta heta} hetarac{dlpha}{lpha^3}d heta\,deta \ \|f\|_2^2 &= \iiint |ig\langle \Phi_{lphaeta heta},fig
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## Some applications to Imaging

### • Candès, Donoho, Starck:

• Image Denoising.





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# Some applications to Imaging

### • Candès, Donoho, Starck:

- Image Denoising.
- Imaging in Astrophysics.





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## Some applications to Imaging

### • Candès, Donoho, Starck:

- Image Denoising.
- Imaging in Astrophysics.
- Donoho, Elad, Querre, Starck: Morphological Component Analysis.



Fig. 5. Top: reconstructed DCT and curvelst components by our method. Bottom: v and u component ming Ward's algorithm.

contaminated by a noise and a stripping artilact (ascured to be the texture in the image) due to the interment determine. As the palaxy is interpine, we used the interpine worket transform instead of curvelst. Figure 3 summarizes the results of the separation where we see a successful isolation of the pulses, the texture of the interfaces are the additive noise.

#### VL PADE ART

This work was primarily impired by the image separation work by Vees and Dator [3]. However, three have been several other arcsenpts to achieve such separation for various needs. We list here some of those works, present burlty their contributions, and reines them to our algorithm.

Whereas piecewise smooth images a are assumed to belong to the Reunded-Valistion (SV) family of functions  $u \in BV(\mathbb{R}^2)$ , texture is known to behave differently. A different approach

September 15, 2004

DRAFT



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# Some applications to Imaging

### • Candès, Donoho, Starck:

- Image Denoising.
- Imaging in Astrophysics.
- Donoho, Elad, Querre, Starck: Morphological Component Analysis.
- Douma, Herrmann, de Hoop...: Seismic Imaging.





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## Curvelets: Construction in the frequency domain

### Amplitude Window

 $W \in C_0^{\infty}(0, \infty)$  nonnegative with support  $[\frac{1}{\alpha_0}, \alpha_0]$  for some  $\alpha_0 > 1$  (usually,  $\alpha_0 = 2$ ), and  $\int_0^{\infty} W(t)^2 \frac{dt}{t} = 1.$ 





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### Phase Window

 $V \in C_0^{\infty}(\mathbb{R})$  nonnegative with support in [-1, 1] and  $||V||_2 = 1.$ 





Curvelet Transforms

Continuous Curvelet Transform



$$W(|\xi|) \, Vig(rac{6}{\pi} rg ig\xiig)$$





$$W(|\xi|) V(rac{48}{\pi} \arg \xi)$$





Curvelet Transforms

Continuous Curvelet Transform



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Background and Motivation Continuous Curvelet Transform Discrete Curvelet Transform



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Background and Motivation Continuous Curvelet Transform Discrete Curvelet Transform



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Background and Motivation Continuous Curvelet Transform Discrete Curvelet Transform

# Dilations, Rotations, Shifts



$$W(|\xi|) V(rac{6}{\pi} \arg \xi)$$





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Francisco Blanco-Silva

Curvelets

Curvelet Transforms

Continuous Curvelet Transform



$$W(|\xi|) \, Vig(rac{6}{\pi} rg ig\xiig)$$





$$W(3|\xi|) V(\frac{6}{\pi} \arg \xi)$$





Background and Motivation Continuous Curvelet Transform Discrete Curvelet Transform



$$W(|\xi|) V(rac{48}{\pi} \arg \xi)$$





$$W(|\xi|)V(rac{48}{\pi}(rg \xi - rac{\pi}{6}))$$





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# Dilations, Rotations, Shifts





 $W(|\xi|) V(\frac{6}{\pi} \arg \xi)$ 









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## Putting it all together

### Definition (Curvelets)

 $\Phi_{\alpha\beta\theta} \colon \mathbb{R}^2 \to \mathbb{C}$  with parameters  $\alpha \in (0, \infty)$  (shape AND scaling),  $\beta \in \mathbb{R}^2$  (location), and  $\theta \in \mathbb{S}^1$  (direction).

$${\mathcal F}(\Phi_{lphaeta heta})(\xi) = \mathit{W}_{lpha}(|\xi|) \mathit{V}_{arphi(lpha)}(rg_{ heta}\,\xi - rg heta) e^{2\pi i (eta\cdot\xi)}$$



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• 
$$W_{lpha}(\xi) = rac{1}{lpha^{1/2}} Wig(rac{|\xi|}{lpha}ig)$$





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$$W_{lpha}(\xi) = rac{1}{lpha^{1/2}} Wig(rac{|\xi|}{lpha}ig)$$

• 
$$V_{\varphi(\alpha)}(\arg_{\theta}\xi - \arg\theta) = \frac{1}{\varphi(\alpha)^{1/2}}V(\frac{\arg_{\theta}\xi - \arg\theta}{\varphi(\alpha)})$$





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•  $V_{\varphi(\alpha)}(\arg_{\theta}\xi - \arg\theta) = rac{1}{\varphi(\alpha)^{1/2}} V(rac{\arg_{\theta}\xi - \arg\theta}{\varphi(\alpha)})$ 

• 
$$\Phi_{lphaeta heta}(x)=\Phi_{lpha0 heta}(x-eta)$$

θ

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A word about the *aspect-ratio* weight function  $\varphi$ 

The width and length of a curvelet obey the anisotropy scaling relation  $\operatorname{width}_{\alpha}/\operatorname{length}_{\alpha} \simeq \varphi(\alpha)$ .





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A word about the *aspect-ratio* weight function  $\varphi$ 



• Candès-Donoho, 1999—2002: width  $\approx \text{length}^2$ .



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A word about the *aspect-ratio* weight function  $\varphi$ 



- Candès-Donoho, 1999—2002: width  $\approx \text{length}^2$ .
- Candès-Donoho, 2003: width  $\approx \text{length}^{1/s}$ , any 0 < s < 1.



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### A word about the *aspect-ratio* weight function $\varphi$



- Candès–Donoho, 1999–2002: width  $\approx \text{length}^2$ .
- Candès–Donoho, 2003: width pprox length $^{1/s}$ , any 0 < s < 1.
- width<sub> $\alpha$ </sub>/length<sub> $\alpha$ </sub>  $\simeq \varphi(\alpha)$ , where  $\varphi: (0, \infty) \to (0, \frac{\pi}{4})$  satisfies:
  - Non-decreasing in  $(0, m_{\varphi})$  and non-increasing in  $(m_{\varphi}, \infty)$ .
  - $\varphi(m_{\varphi}) = M < \frac{\pi}{4}, \lim_{\alpha \to 0} \varphi(\alpha) = 0 \text{ and } \lim_{\alpha \to \infty} \varphi(\alpha) = 0.$
  - Neither  $\varphi(\cdot)|_{(m_{\varphi},\infty)}$  nor  $\varphi(1/\cdot)|_{(0,m_{\varphi})}$  decrease rapidly.

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## Gathering Information

### Definition (Curvelet Coefficient)

For each choice of parameters  $\alpha \in (0, \infty)$ ,  $\beta \in \mathbb{R}^2$  and  $\theta \in \mathbb{S}^1$ , the inner product

$$\langle f, \mathbf{\Phi}_{lphaeta heta} 
angle = \int f(x) \overline{\mathbf{\Phi}_{lphaeta heta}(x)} \, dx$$

offers local information of a function  $f \in L_2(\mathbb{R}^2)$  at the location  $\beta$ , in the direction  $\theta$ , and frequency  $(\alpha/\alpha_0, \alpha_0\alpha)$ .



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## Gathering Information

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### $\langle u, \Phi_{lphaeta heta} angle$

offers local information of a tempered distribution  $\nu \in S'(\mathbb{R}^2)$  at the location  $\beta$ , in the direction  $\theta$ , and frequency  $(\alpha/\alpha_0, \alpha_0 \alpha)$ .



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# Resolution of the identity for CCT in $L_2(\mathbb{R}^2)$

### Calderón formula for CCT

For any function  $f \in L_2(\mathbb{R}^2)$ ,

$$f(x) = \int_0^\infty \int_{\mathbb{S}^1} \int_{\mathbb{R}^2} \langle f, \Phi_{lphaeta heta} 
angle \Phi_{lphaeta heta}(x) \, deta \, d\sigma( heta) \, dlpha$$



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Parseval's Formula for CCT in  $L_2(\mathbb{R}^2)$ 

### Inner product identity

$$\langle f,g
angle = \, \int_0^\infty \, \int_{\mathbb{S}^1} \, \int_{\mathbb{R}^2} \langle f, \mathbf{\Phi}_{lphaeta heta}
angle \overline{\langle g, \mathbf{\Phi}_{lphaeta heta}
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Parseval's Formula for CCT in  $L_2(\mathbb{R}^2)$ 

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angle} \, deta \, d\sigma( heta) \, dlpha$$

#### In particular,

Parseval's Formula for CCT
$\ f\ ^2_{L_2(\mathbb{R}^2)} = \int_0^\infty \int_{\mathbb{S}^1} \int_{\mathbb{R}^2}  \langle f, oldsymbol{\Phi}_{lphaeta heta}  angle ^2 deta  d\sigma( heta) dlpha$



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### Discretization of the Curvelet Transform I





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### Discretization of the Curvelet Transform I





Background and Motivation Continuous Curvelet Transform Discrete Curvelet Transform

### Discretization of the Curvelet Transform I



#### Discretization

•  $(0,\infty)$ : For each  $n\in\mathbb{Z},$  $lpha_n=lpha_0^n.$ 

### • \$<sup>1</sup>:

• 
$$\varphi_n = \inf_{z \in \mathbb{Z}} \{ \frac{1}{2\pi z} \ge \varphi(\alpha_n) \}.$$

• Chosen n, for each 
$$k \in \mathbb{Z}$$
,  
 $heta_{nk} = e^{ik\varphi_n}.$ 



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$$n,$$
 for each  $k\in\mathbb{Z},$   $heta_{nk}=e^{ikarphi_n}.$ 

• 
$$\mathbb{R}^2$$
: Chosen *n*, for each  $z \in \mathbb{Z}^2, \beta_{nz} = \frac{\pi}{\alpha_{n+1}} z.$ 



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### Discretization of the Curvelet Transform II

#### Amplitude and Phase Windows

•  $W \in C_0^{\infty}(0, \infty)$  nonnegative with supp  $W = \left[\frac{1}{\alpha_0}, \alpha_0\right]$ , and  $W(u)^2 + W(\alpha_0 u)^2 = 1$  for  $\frac{1}{\alpha_0} \le u \le 1$ .



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- $V \in C_0^{\infty}(\mathbb{R})$  nonnegative with supp V = [-1, 1], and  $V(t)^2 + V(t-1)^2 = 1$  for  $0 \le t < 1$ .



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#### Definition

$$\boldsymbol{\phi}_{nk\boldsymbol{z}} = \left(rac{\varphi_n^{1/2}}{2lpha_0^{n/2+1}}
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Discretization of the Curvelet Transform to obtain tight frames in  $L_2(\mathbb{R}^2)$ 

#### Theorem

$$\{oldsymbol{\phi}_{nkoldsymbol{z}}:n\in\mathbb{Z};k=1,\ldots,2\pi/arphi_n;oldsymbol{z}\in\mathbb{Z}^2\}$$
 .

is a tight frame in  $L_2(\mathbb{R}^2)$  with frame bound 1.

$$\|f\|^2_{L_2(\mathbb{R}^2)} = \sum_{n\in\mathbb{Z}}\sum_{k=1}^{2\pi/arphi_n}\sum_{oldsymbol{z}\in\mathbb{Z}^2}|\langle f,oldsymbol{\phi}_{nkoldsymbol{z}}
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angle|^2$$

$$f = \sum_{n \in \mathbb{Z}} \sum_{k=1}^{2\pi/arphi_n} \sum_{oldsymbol{z} \in \mathbb{Z}^2} \langle f, oldsymbol{\phi}_{nkoldsymbol{z}} 
angle oldsymbol{\phi}_{nkoldsymbol{z}}.$$



Curvelets and Singularities Curvelets and Cartoons Curvelets and Besov Spaces

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Curvelets and Singularities Curvelets and Cartoons Curvelets and Besov Spaces

$$egin{aligned} &\langle \delta,g
angle &= g(0) \ &igodot \langle \delta, \Phi_{lpha 0 heta}
angle &= \Theta(rac{1}{arphi(lpha)}) \ & ext{for all } heta \in \mathbb{S}^1 ext{ as } lpha o \infty. \end{aligned}$$



Curvelets and Singularities Curvelets and Cartoons Curvelets and Besov Spaces

$$\begin{array}{rcl} \langle \delta,g\rangle &=& g(0) \\ \bullet & \langle \delta, \Phi_{\alpha 0\theta} \rangle = \Theta(\frac{1}{\varphi(\alpha)}) \\ \text{for all } \theta \in \mathbb{S}^1 \text{ as } \alpha \to \infty. \\ \bullet & \lim_{\alpha \to \infty} \langle \delta, \Phi_{\alpha \beta \theta} \rangle = 0 \text{ (rapidly!)} \\ \text{for } \beta \neq 0 \text{ and all } \theta \in \mathbb{S}^1. \end{array}$$



Curvelets and Singularities Curvelets and Cartoons Curvelets and Besov Spaces

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$$egin{aligned} & \gamma_s(x) = |x|^s, -2 < s < 0 \ \end{array} \ & \langle \gamma_s, \Phi_{lpha 0 heta} 
angle = \Theta(rac{1}{lpha^{2+s} arphi(lpha)^2}) \ & ext{for all } heta \in \mathbb{S}^1 ext{ as } lpha o \infty. \end{aligned}$$



Curvelets and Singularities Curvelets and Cartoons Curvelets and Besov Spaces

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Curvelets and Singularities Curvelets and Cartoons Curvelets and Besov Spaces

$$\begin{array}{l} \langle \nu_x, g \rangle = \int_{\mathbb{R}} g(x,0) \, dx \\ \bullet \langle \nu_x, \Phi_{\alpha(\lambda,0)} \frac{\pi}{2} \rangle = \Theta(\frac{1}{\alpha \varphi(\alpha)^2}) \\ \text{as } \alpha \to \infty. \\ \bullet \lim_{\alpha \to \infty} \langle \nu_x, \Phi_{\alpha\beta(\theta \neq \frac{\pi}{2})} \rangle = 0 \\ \bullet \lim_{\alpha \to \infty} \langle \nu_x, \Phi_{\alpha\beta} \frac{\pi}{2} \rangle = 0 \\ \text{(rapidly!)} \\ \text{otherwise.} \end{array}$$



Curvelets and Singularities Curvelets and Cartoons Curvelets and Besov Spaces

$$\langle \nu_x, g \rangle = \int_{\mathbb{R}} g(x, 0) \, dx$$
  
•  $\langle \nu_x, \Phi_{\alpha(\lambda,0)} \frac{\pi}{2} \rangle = \Theta(\frac{1}{\alpha \varphi(\alpha)^2})$   
as  $\alpha \to \infty$ .  
•  $\lim_{\alpha \to \infty} \langle \nu_x, \Phi_{\alpha\beta(\theta \neq \frac{\pi}{2})} \rangle \stackrel{=}{\underset{(rapidly!)}{=}} 0$   
•  $\lim_{\alpha \to \infty} \langle \nu_x, \Phi_{\alpha\beta} \frac{\pi}{2} \rangle = 0$  (rapidly!) otherwise.

$$\begin{array}{rcl} H(x,y) &=& \mathbf{1}_{\{y \geq 0\}} \\ \bullet \langle H, \Phi_{\alpha(\lambda,0)} \frac{\pi}{2} \rangle &=& \Theta(\frac{1}{\varphi(\alpha)^2}) \\ \text{as } \alpha \to \infty. \\ \bullet & \lim_{\alpha \to \infty} \langle H, \Phi_{\alpha\beta(\theta \neq \frac{\pi}{2})} \rangle = \mathbf{0} \\ \bullet & \lim_{\alpha \to \infty} \langle H, \Phi_{\alpha\beta} \frac{\pi}{2} \rangle = 0 \text{ (rapidly!)} \\ \bullet & \inf_{\alpha \to \infty} \langle H, \Phi_{\alpha\beta} \frac{\pi}{2} \rangle = 0 \text{ (rapidly!)} \\ \text{otherwise.} \end{array}$$



## Microlocal Analysis

#### Theorem (Candès, Donoho)

The  $\alpha \to \infty$  asymptotics of the Continuous Curvelet Transform precisely resolve the wavefront set of tempered distributions.



## Microlocal Analysis

#### Theorem (Candès, Donoho)

The  $\alpha \to \infty$  asymptotics of the Continuous Curvelet Transform precisely resolve the wavefront set of tempered distributions.

Given a tempered distribution  $\nu \in \mathcal{S}'(\mathbb{R}^2)$ , let

$$\mathcal{R} = \{ (eta_0, heta_0) \in \mathbb{R}^2 imes \mathbb{S}^1 : \langle 
u, \mathbf{\Phi}_{lphaeta heta} 
angle ext{ decays rapidly} \ ext{near } (eta_0, heta_0) ext{ as } lpha o \infty \}$$

Then  $WF(\nu)$  is the complement of  $\mathcal{R}$ .



Curvelets and Cartoons Curvelets and Besov Spaces

### Who cares?





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# Outline

#### Curvelet Transforms

- Background and Motivation
- Continuous Curvelet Transform
- Discrete Curvelet Transform

#### 2 Analysis with Curvelets

- Curvelets and Singularities
- Curvelets and Cartoons
- Curvelets and Besov Spaces



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## Nonlinear Approximation to "cartoon" functions



A. C. Calder *et al.* High-Performance Reactive Fluid Flow Simulations Using Adaptive Mesh Refinement on Thousands of Processors.

Silicon abundances (ashes)

• Approximation by selecting the N largest terms in the Fourier series:

$$\left\|f-f_{N}^{\mathcal{F}}\right\|_{L_{2}\left(\mathbb{R}^{2}
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# <u>Nonlinear Approximation to "cartoon" functions</u>



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• Approximation by selecting the N largest terms in the Wavelet Decomposition:

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• Approximation by superposition of N triangles with arbitrary shapes and locations:

$$\left\|f-f_N^{\mathcal{T}}
ight\|_{L_2(\mathbb{R}^2)}=\Theta(N^{-1})$$

• Approximation by selecting the N largest terms in the Curvelet Decomposition:

$$\|f - f_N^{\mathcal{C}}\|_{L_2(\mathbb{R}^2)} = \Theta(N^{-1}(\log N)^{3/2})$$



# Outline

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## How smooth is this function?





## **Besov Spaces**

#### Definition

Given  $f : \mathbb{R}^d \to \mathbb{R}$ , for  $h \in \mathbb{R}^d$ , set for any  $n \in \mathbb{N}$ ,

$$\Delta^n_h f(x) = \Delta^{n-1}_h \Delta_h f(x) = \sum_{k=0}^n (-1)^{n-k} {n \choose k} f(x+kh).$$



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For  $\eta > 0$ , set  $\omega_{\eta}(f, t)_r = \sup_{|h| < t} \left\| \Delta_h^{\lceil \eta \rceil} f \right\|_{L_r(\mathbb{R}^d)}$ .



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 $\begin{array}{l} \text{For } \eta > 0 \text{, set } \omega_\eta(f,t)_r = \sup_{|h| < t} \left\| \Delta_h^{\lceil \eta \rceil} f \right\|_{L_r(\mathbb{R}^d)}. \\ f \in B^\eta_q(L_r(\mathbb{R}^d)) \text{ if } \end{array}$ 

$$\|f\|_{L_r(\mathbb{R}^d)}+\Big\{\int_0^\infty ig(t^{-\eta}\omega_\eta(f,t)_r)^qrac{dt}{t}\Big\}^{1/q}<\infty$$



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## **Embedding Theorems**

### Theorem (DeVore, Popov)

If  $\eta, r, p > 0$  are related by  $\frac{1}{r} = \frac{\eta}{d} + \frac{1}{p}$ , then  $B_p^{\eta}(L_r(\mathbb{R}^d))$  is continuously embedded in  $L_p(\mathbb{R}^d)$ .





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## **Embedding Theorems**

#### Corollary (DeVore, Popov)

If  $\eta, r > 0$  are related by  $\frac{1}{r} = \frac{\eta}{2} + \frac{1}{2}$ , then  $B_r^{\eta}(L_r(\mathbb{R}^2))$  is continuously embedded in  $L_2(\mathbb{R}^2)$ .





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## Approximation Theorems

#### Theorem

$$f \in B_r^{\eta}(L_r(\mathbb{R}^2))$$
 if and only if  $\|f - f_N^{\mathcal{W}}\|_{L_2(\mathbb{R}^2)} = \Theta(N^{-\eta/2}).$ 



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## Approximation Theorems

#### Theorem

$$f \in B^{\eta}_{r}(L_{r}(\mathbb{R}^{2})) ext{ if and only if } \|f - f^{\mathcal{W}}_{N}\|_{L_{2}(\mathbb{R}^{2})} = \Theta(N^{-\eta/2}).$$

or equivalently,  $\log \|f - f_N^{\mathcal{W}}\|_{L_2(\mathbb{R}^2)} = \Theta(-\frac{\eta}{2}\log N).$ 



Curvelet Transforms

Analysis with Curvelets Curvelets and Besov Spaces Computation of Smoothness via Nonlinear

Approximation with Wavelets





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# Computation of Smoothness via Nonlinear Approximation with Wavelets





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# Computation of Smoothness via Nonlinear Approximation with Wavelets





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# Computation of Smoothness via Nonlinear Approximation with Wavelets



slope  $\approx -0.3072$  $\eta \approx 0.6144$ 



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## Experiments





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## Experiments





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### Experiments





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## Which one is the one?

slope  $\approx -0.3072$  $\eta \approx 0.6144$ 

slope  $\approx -0.2031$  $\eta \approx 0.5077$ 



