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Maple Worksheet for Qualitative Analysis for Nonlinear Systems (Section 6.7 in Ledder)

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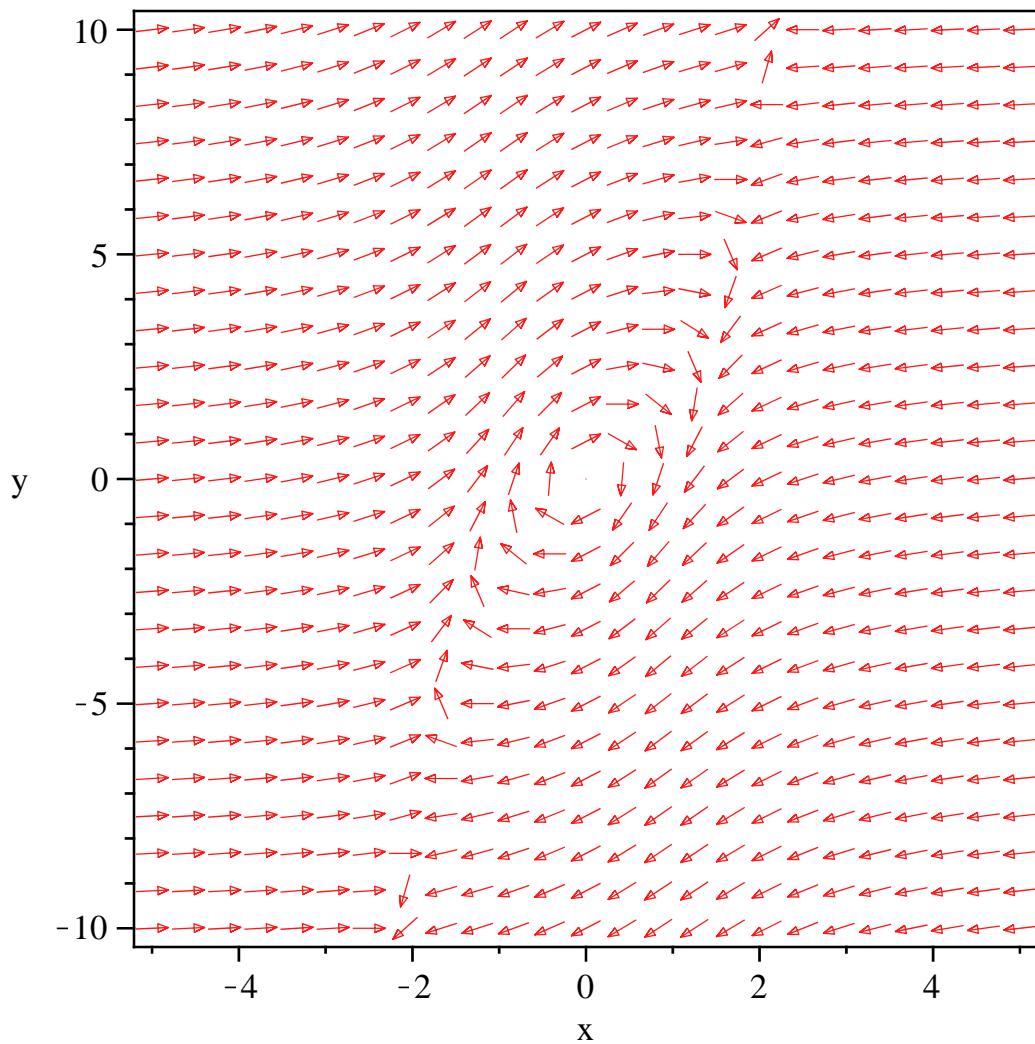
```
>
> restart;
> with( DEtools ):
> with( plots ):
> with( LinearAlgebra ):
> with( plottools ):
>
> SYS2 := [
>   diff( x(t), t ) = f( x(t), y(t) ),
>   diff( y(t), t ) = g( x(t), y(t) )
> ];
> SYS3 := [
>   diff( x(t), t ) = f( x(t), y(t), z(t) ),
>   diff( y(t), t ) = g( x(t), y(t), z(t) ),
>   diff( z(t), t ) = h( x(t), y(t), z(t) )
> ];
>
>
```

► # 2 (p. 408)

► # 3 (p. 408)

▼ # 6 (p. 408)

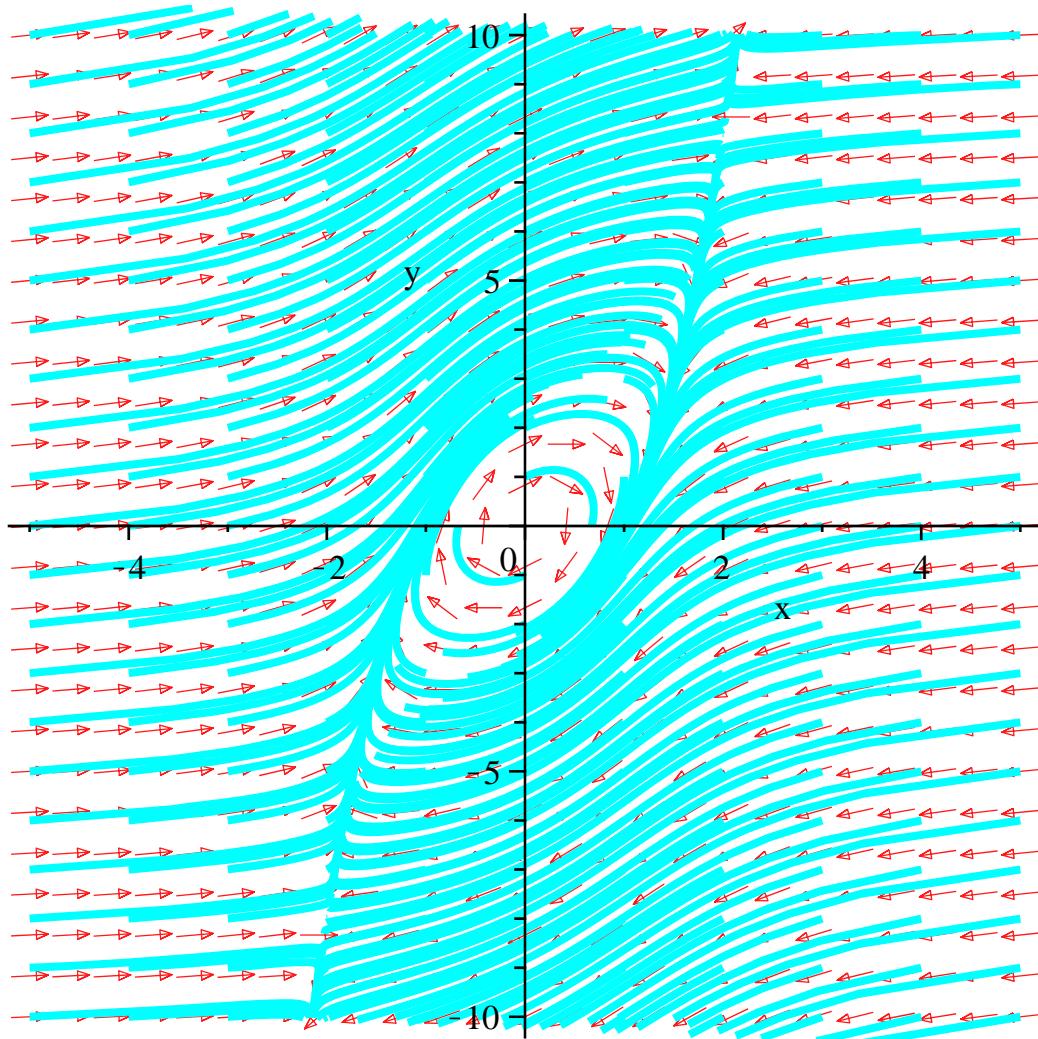
```
> f := (x,y) -> y-x^3;
> g := (x,y) -> y-4*x;
f:=(x,y)→y-x3
g:=(x,y)→y-4 x
(3.1)
>
> DEplot( SYS2, [x(t),y(t)], t=0..1, x=-5..5, y=-10..10,
arrows=medium, dirgrid=[25,25], axes=boxed );
```



```

>
> IC := [ seq( seq( [0,a,b], b=[-$10..10] ), a=[-$5..5] ) ]:
>
> DEplot( SYS2, [x(t),y(t)], t=0..1, x=-5..5, y=-10..10, IC,
          arrows=medium, linecolor=cyan,
          dirgrid=[25,25], stepsize=0.05
        );

```



```
> EqSolns := solve( [f(x,y)=0,g(x,y)=0], [x,y] );
EqSolns := [[x = 0, y = 0], [x = 2, y = 8], [x = -2, y = -8]] (3.2)
```

```
>
> J := VectorCalculus:-Jacobian( [f(x,y),g(x,y)], [x,y] );
J := 
$$\begin{bmatrix} -3x^2 & 1 \\ -4 & 1 \end{bmatrix} (3.3)$$

```

```
> J1 := eval( J, EqSolns[1] );
J1 := 
$$\begin{bmatrix} 0 & 1 \\ -4 & 1 \end{bmatrix} (3.4)$$

```

```
> Eigenvalues( J1 );
(3.5)
```

$$\begin{bmatrix} \frac{1}{2} + \frac{1}{2} I\sqrt{15} \\ \frac{1}{2} - \frac{1}{2} I\sqrt{15} \end{bmatrix} \quad (3.5)$$

```
=>
> J2 := eval( J, EqSolns[2] );
J2 := 
$$\begin{bmatrix} -12 & 1 \\ -4 & 1 \end{bmatrix} \quad (3.6)$$

```

```
=> Eigenvalues( J2 );

$$\begin{bmatrix} -\frac{11}{2} + \frac{3}{2}\sqrt{17} \\ -\frac{11}{2} - \frac{3}{2}\sqrt{17} \end{bmatrix} \quad (3.7)$$

```

```
=>
> J3 := eval( J, EqSolns[3] );
J3 := 
$$\begin{bmatrix} -12 & 1 \\ -4 & 1 \end{bmatrix} \quad (3.8)$$

```

```
=> Eigenvalues( J3 );

$$\begin{bmatrix} -\frac{11}{2} + \frac{3}{2}\sqrt{17} \\ -\frac{11}{2} - \frac{3}{2}\sqrt{17} \end{bmatrix} \quad (3.9)$$

```

```
[>
```