

Theorem (Granville, Schinzel, F.): *An algorithm exists for determining if a given nonreciprocal polynomial $f(x) \in \mathbb{Z}[x]$ is irreducible and that runs in time $O_{r,H}(\log n (\log \log n)^2 |\log \log \log n|)$.*

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$$f(x) \neq \pm x^{\deg f} f(1/x)$$

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- If f has a cyclotomic factor, then the algorithm will detect this and output an $m \in \mathbb{Z}^+$ with $\Phi_m(x)$ a factor.
- If f has no cyclotomic factor but has a reciprocal factor, then the algorithm will give an explicit reciprocal factor.
- Otherwise, the algorithm outputs the complete factorization of $f(x)$ into irreducible polynomials over \mathbb{Q} .

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Theorem (Granville, Schinzel, F.): *There is an algorithm that has the following property: given $f(x) = \sum_{j=0}^r a_j x^{d_j} \in \mathbb{Z}[x]$ of degree $n > 1$ and with $r + 1$ terms, the algorithm determines if $f(x)$ has a cyclotomic factor in running time $O_{r,H}(\log n (\log \log n)^2 |\log \log \log n|)$.*

There is a cyclotomic factor of $f(x) = \sum_{j=0}^r a_j x^{d_j}$ if and only if \exists a partition

$$\{0, 1, \dots, r\} = J_1 \dot{\cup} J_2 \dot{\cup} \dots \dot{\cup} J_s$$

such that if, for $1 \leq i \leq s$,

$$\sum_{j \in J_i} a_j x^{d_j} = x^{b_i} g_i(x^{e_i}), \quad M_i = \dots$$

then there are $m_i \in M_i$ for which

$$m_0 = \prod_{p | m_1 \cdots m_s} \max_{1 \leq i \leq s} \{p^k : p^k \parallel m_i e_i\}$$

satisfies

$$m_0 = m_i \gcd(m_0, e_i), \quad i \in \{1, 2, \dots, s\}.$$

- If f has no cyclotomic factor but has a reciprocal factor, then the algorithm will give an explicit reciprocal factor.
-

We'll come back to this.

- Otherwise, the algorithm outputs the complete factorization of $f(x)$ into irreducible polynomials over \mathbb{Q} .
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$$f(x) = \sum_{j=0}^r a_j x^{d_j}$$

f has no reciprocal factors
(other than constants)

- Otherwise, the algorithm outputs the complete factorization of $f(x)$ into irreducible polynomials over \mathbb{Q} .
-

$$f(x) = \sum_{j=0}^r a_j x^{d_j}$$

$$\begin{aligned} F &= F(x_1, x_2, \dots, x_r) \\ &= a_r x_r + \dots + a_1 x_1 + a_0, \end{aligned}$$

$$f(x) = F(x^{d_1}, x^{d_2}, \dots, x^{d_r})$$

$$f(x) = \sum_{j=0}^r a_j x^{d_j}, \quad F(x_1, \dots, x_r) = a_0 + \sum_{j=1}^r a_j x_j$$

$$(1) \quad \begin{pmatrix} d_1 \\ \vdots \\ d_r \end{pmatrix} = (m_{ij})_{r \times t} \begin{pmatrix} v_1 \\ \vdots \\ v_t \end{pmatrix}$$

$$d_i = m_{i1}v_1 + \dots + m_{it}v_t, \quad 1 \leq i \leq r$$

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(m_{ij}) will come from a finite set depending only on F

$v_j \in \mathbb{Z}$ show exist for some (m_{ij})

$$f(x) = \sum_{j=0}^r a_j x^{d_j}, \quad F(x_1, \dots, x_r) = a_0 + \sum_{j=1}^r a_j x_j$$

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$$F(y_1^{m_{11}} \dots y_t^{m_{1t}}, \dots, y_1^{m_{r1}} \dots y_t^{m_{rt}})$$

$$y_j = x^{v_j}, \quad 1 \leq j \leq t$$

$$F(x^{d_1}, x^{d_2}, \dots, x^{d_r}) = f(x)$$

Thought: A factorization in $\mathbb{Z}[y_1, \dots, y_t]$ implies a factorization of $f(x)$ in $\mathbb{Z}[x]$.

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Counter-Thought: We want m_{ij} and v_j in \mathbb{Z} , but not necessarily positive.

$$f(x) = \sum_{j=0}^r a_j x^{d_j}, \quad F(x_1, \dots, x_r) = a_0 + \sum_{j=1}^r a_j x_j$$


$$(1) \quad d_i = m_{i1}v_1 + \dots + m_{it}v_t, \quad 1 \leq i \leq r$$

$$J F(y_1^{m_{11}} \dots y_t^{m_{1t}}, \dots, y_1^{m_{r1}} \dots y_t^{m_{rt}})$$

Do what you have to do to make
this in $\mathbb{Z}[y_1, y_2, \dots, y_t]$.

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$$y_1^{u_1} \dots y_t^{u_t} F(y_1^{m_{11}} \dots y_t^{m_{1t}}, \dots, y_1^{m_{r1}} \dots y_t^{m_{rt}})$$

Recall: Factor and substitute $y_j = x^{v_j}$.

$$f(x) = \sum_{j=0}^r a_j x^{d_j}, \quad F(x_1, \dots, x_r) = a_0 + \sum_{j=1}^r a_j x_j$$

$$(1) \quad d_i = m_{i1}v_1 + \dots + m_{it}v_t, \quad 1 \leq i \leq r$$

$$(2) \quad y_1^{u_1} \cdots y_t^{u_t} F(y_1^{m_{11}} \cdots y_t^{m_{1t}}, \dots, y_1^{m_{r1}} \cdots y_t^{m_{rt}}) \\ = F_1(y_1, \dots, y_t) \cdots F_s(y_1, \dots, y_t)$$

$$(3) \quad f(x) = \prod_{i=1}^s x^{w_i} F_i(x^{v_1}, \dots, x^{v_t})$$

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Conclusion: (1) and (2) imply (3)

$$f(x) = \sum_{j=0}^r a_j x^{d_j}, \quad F(x_1, \dots, x_r) = a_0 + \sum_{j=1}^r a_j x_j$$

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Question: Are $s - 1$ of the factors 1?

Theorem (A. Schinzel, 1969): *Fix*

$$F = a_r x_r + \cdots + a_1 x_1 + a_0,$$

with a_j nonzero integers. There exists a finite computable set of matrices S with integer entries, depending only on F , with the following property:

Suppose the vector

$$\vec{d} = \langle d_1, d_2, \dots, d_r \rangle \in \mathbb{Z}^r,$$

with $d_r > \cdots > d_1 > 0$, is such that

$$f(x) = F(x^{d_1}, x^{d_2}, \dots, x^{d_r})$$

has no non-constant reciprocal factor.

Then $\exists r \times t$ matrix $M = (m_{ij}) \in S$ of rank $t \leq r$ and a vector

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such that

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holds and the factorization given by

$$\begin{aligned} & y_1^{u_1} \cdots y_t^{u_t} F(y_1^{m_{11}} \cdots y_t^{m_{1t}}, \dots, y_1^{m_{r1}} \cdots y_t^{m_{rt}}) \\ &= F_1(y_1, \dots, y_t) \cdots F_s(y_1, \dots, y_t) \end{aligned}$$

in $\mathbb{Z}[y_1, \dots, y_t]$ into irreducibles implies

$$f(x) = \prod_{i=1}^s x^{w_i} F_i(x^{v_1}, \dots, x^{v_t})$$

as a product of polynomials in $\mathbb{Z}[x]$ each of which is either irreducible over \mathbb{Q} or a constant.

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- If f has no cyclotomic factor but has a reciprocal factor, then the algorithm will give an explicit reciprocal factor.
-

We've checked:

f does not have a cyclotomic factor.

We want to know:

Does f have a reciprocal factor?

- If f has no cyclotomic factor but has a reciprocal factor, then the algorithm will give an explicit reciprocal factor.
-

Does f have a reciprocal factor?

Suppose $w(x)$ is a reciprocal factor.

$$\begin{aligned}w(\alpha) = 0 &\implies \alpha \neq 0 \text{ and } w(1/\alpha) = 0 \\ &\implies f(\alpha) = 0 \text{ and } g(\alpha) = 0,\end{aligned}$$

where $g(x) = x^{\deg f} f(1/x) \neq f(x)$

We want to compute $\gcd(f, g)$.

- If f has no cyclotomic factor but has a reciprocal factor, then the algorithm will give an explicit reciprocal factor.
-

In general, if f and g are sparse polynomials around degree n in $\mathbb{Z}[x]$, how does one compute $\gcd(f, g)$?

Some items to keep in mind:

→ The Euclidean algorithm will run in time that is polynomial in n , not $\log n$.

- If f has no cyclotomic factor but has a reciprocal factor, then the algorithm will give an explicit reciprocal factor.
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In general, if f and g are sparse polynomials around degree n in $\mathbb{Z}[x]$, how does one compute $\gcd(f, g)$?

Some items to keep in mind:



→ Plaisted (1977) has shown that this problem is at least as hard as any problem in NP.

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Plaisted's takes f and g to be divisors of $x^N - 1$ where N is a product of small primes.

We are interested in the case that both f and g do not have a cyclotomic factor.

Problem: Find an algorithm which takes given sparse polynomials

$$f(x) = \sum_{j=1}^k a_j x^{d_j}, \quad g(x) = \sum_{j=1}^k b_j x^{d_j},$$

in $\mathbb{Z}[x]$ having no cyclotomic factors, with

$$d_1 = 0 < d_2 < \cdots < d_k,$$

and computes $\gcd(f, g)$ in time that is polynomial in $\log d_k$.

Theorem (Granville, Schinzel, F.): *There is an algorithm which takes as input two polynomials $f(x)$ and $g(x)$ in $\mathbb{Z}[x]$, each of degree $\leq n$ and height $\leq H$ and having $\leq r + 1$ nonzero terms, with at least one of $f(x)$ and $g(x)$ free of any cyclotomic factors, and outputs the value of $\gcd_{\mathbb{Z}}(f(x), g(x))$ and runs in time $O_{r,H}(\log n)$.*

Corollary: *If $f(x), g(x) \in \mathbb{Z}[x]$ with $f(x)$ or $g(x)$ not divisible by a cyclotomic polynomial, then $\gcd_{\mathbb{Z}}(f(x), g(x))$ has $O_{r,H}(1)$ terms.*

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Note that if a and b are relatively prime positive integers, then

$$\begin{aligned} & \gcd(x^{ab} - 1, (x^a - 1)(x^b - 1)) \\ &= \frac{(x^a - 1)(x^b - 1)}{x - 1}, \end{aligned}$$

which can have arbitrarily many terms.

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$$f(x) = \sum_{j=1}^k a_j x^{d_j} \quad \rightarrow \quad F_{\mathbb{Z}}(\vec{x}) = \sum_{j=1}^k a_j x_j$$

Lemma (Bombieri and Zannier): *Let*

$$F_1, F_2 \in \mathbb{Q}[x_1, \dots, x_k]$$

be coprime polynomials. There exists a number $c_1(F_1, F_2)$ with the following property. If $\vec{u} = \langle u_1, \dots, u_k \rangle \in \mathbb{Z}^k$, $\xi \neq 0$ is algebraic and

$$F_1(\xi^{u_1}, \dots, \xi^{u_k}) = F_2(\xi^{u_1}, \dots, \xi^{u_k}) = 0,$$

then either ξ is a root of unity or there exists a non-zero vector $\vec{v} \in \mathbb{Z}^k$ having length at most c_1 and orthogonal to \vec{u} .

$$f(x) = \sum_{j=1}^k a_j x^{d_j} \quad \rightarrow \quad F_1(\vec{x}) = \sum_{j=1}^k a_j x_j$$

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There exists a number $c_1(\vec{a}, \vec{b}, k)$ with the following property. If $f(\xi) = g(\xi) = 0$, then there exists a non-zero vector $\vec{v} \in \mathbb{Z}^k$ having length at most c_1 and orthogonal to \vec{u} .

$$\vec{u} = \langle d_1, \dots, d_k \rangle$$

Note: It is important that c_1 is computable.

Idea: The lattice of vectors orthogonal to \vec{v} is $(k-1)$ -dimensional so that there exists a vector $\langle e_1, \dots, e_{k-1} \rangle$ and a matrix \mathcal{M} in \mathbb{Z}^{k-1} satisfying

$$\begin{pmatrix} d_1 \\ d_2 \\ \vdots \\ d_k \end{pmatrix} = \mathcal{M} \cdot \begin{pmatrix} e_1 \\ e_2 \\ \vdots \\ e_{k-1} \end{pmatrix}.$$

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So

$$d_i = \sum_{j=1}^{k-1} m_{ij} e_j,$$

with the $m_{ij} \in \mathbb{Z}$ bounded.

$$d_i = \sum_{j=1}^{k-1} m_{ij} e_j$$

$$x^{d_i} = \prod_{j=1}^{k-1} (x^{e_j})^{m_{ij}}$$

$$d_i = \sum_{j=1}^{k-1} m_{ij} e_j \quad x^{d_i} = \prod_{j=1}^{k-1} (x^{e_j})^{m_{ij}}$$

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$$F_1^{(2)}(x^{e_1}, \dots, x^{e_{k-1}}) = f(x)$$

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